Operating Instructions

VEGAPULS 65

4 … 20 mA/HART - four-wire

Document ID:
36516

Radar

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Safety instructions for Ex areas

Please note the Ex-specific safety information for installation and operation in Ex areas. These safety instructions are part of the operating instructions manual and come with the Ex-approved instruments.

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1 About this document

1.1 Function

This operating instructions manual provides all the information you need for mounting, connection and setup as well as important instructions for maintenance and fault rectification. Please read this information before putting the instrument into operation and keep this manual accessible in the immediate vicinity of the device.

1.2 Target group

This operating instructions manual is directed to trained qualified personnel. The contents of this manual should be made available to these personnel and put into practice by them.

1.3 Symbolism used

Information, tip, note
This symbol indicates helpful additional information.

Caution: If this warning is ignored, faults or malfunctions can result.
Warning: If this warning is ignored, injury to persons and/or serious damage to the instrument can result.
Danger: If this warning is ignored, serious injury to persons and/or destruction of the instrument can result.

Ex applications
This symbol indicates special instructions for Ex applications.

- **List**
  The dot set in front indicates a list with no implied sequence.

→ **Action**
This arrow indicates a single action.

1 **Sequence**
Numbers set in front indicate successive steps in a procedure.

2 For your safety

2.1 Authorised personnel

All operations described in this operating instructions manual must be carried out only by trained specialist personnel authorised by the plant operator.

During work on and with the device the required personal protective equipment must always be worn.

2.2 Appropriate use

VEGAPULS 65 is a sensor for continuous level measurement.

You can find detailed information on the application range in chapter "*Product description*".

Operational reliability is ensured only if the instrument is properly used according to the specifications in the operating instructions manual as well as possible supplementary instructions.

2.3 Warning about misuse

Inappropriate or incorrect use of the instrument can give rise to application-specific hazards, e.g. vessel overfill or damage to system components through incorrect mounting or adjustment.

2.4 General safety instructions

This is a state-of-the-art instrument complying with all prevailing regulations and guidelines. The instrument must only be operated in a technically flawless and reliable condition. The operator is responsible for the trouble-free operation of the instrument.

During the entire duration of use, the user is obliged to determine the compliance of the necessary occupational safety measures with the current valid rules and regulations and also take note of new regulations.

The safety instructions in this operating instructions manual, the national installation standards as well as the valid safety regulations and accident prevention rules must be observed by the user.

For safety and warranty reasons, any invasive work on the device beyond that described in the operating instructions manual may be carried out only by personnel authorised by the manufacturer. Arbitrary conversions or modifications are explicitly forbidden.

The safety approval markings and safety tips on the device must also be observed.

Depending on the instrument version, the emitting frequencies are in the C or K band range. The low emitting frequencies are far below the internationally approved limit values. When used correctly, there is no danger to health.

2.5 CE conformity

The device fulfills the legal requirements of the applicable EC guidelines. By affixing the CE marking, we confirm successful testing of the product.

You can find the conformity certificate in the download section of our homepage.

The instrument is designed for use in an industrial environment. Nevertheless, electromagnetic interference from electrical conductors and radiated emissions must be taken into account, as is usual with a class A instrument according to EN 61326-1. If the instrument is used in a different environment, its electromagnetic compatibility with other devices must be ensured by suitable measures.

2.6 NAMUR recommendations

NAMUR is the automation technology user association in the process industry in Germany. The published NAMUR recommendations are accepted as the standard in field instrumentation.

The device fulfills the requirements of the following NAMUR recommendations:

- NE 21 – Electromagnetic compatibility of equipment
- NE 43 – Signal level for malfunction information from measuring transducers
- NE 53 – Compatibility of field devices and indicating/adjustment components
- NE 107 - Self-monitoring and diagnosis of field devices

For further information see www.namur.de.

2.7 Radio license for Europe

The instrument is approved according to EN 302372-1/2 (2006-04) for use in closed vessels.

2.8 Radio license for USA/Canada

The instrument is in conformity with part 15 of the FCC regulations. Take note of the following two regulations:

- The device must not generate interfering emissions, and
- The device must be non-sensitive to interfering immissions, including those that may cause undesirable operating conditions.

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Modifications not expressly approved by the manufacturer will lead to expiry of the operating licence according to FCC/IC.

The instrument is in conformity with RSS-210 of the IC regulations.

The instrument may only be operated in closed vessels made of metal, concrete, or fibre-reinforced plastic.

2.9 Environmental instructions

Protection of the environment is one of our most important duties. That is why we have introduced an environment management system with the goal of continuously improving company environmental protection. The environment management system is certified according to DIN EN ISO 14001.

Please help us fulfil this obligation by observing the environmental instructions in this manual:

- Chapter "*Packaging, transport and storage*"
- Chapter "*Disposal*"

3 Product description

3.1 Structure

Type label

The type label contains the most important data for identification and use of the instrument:

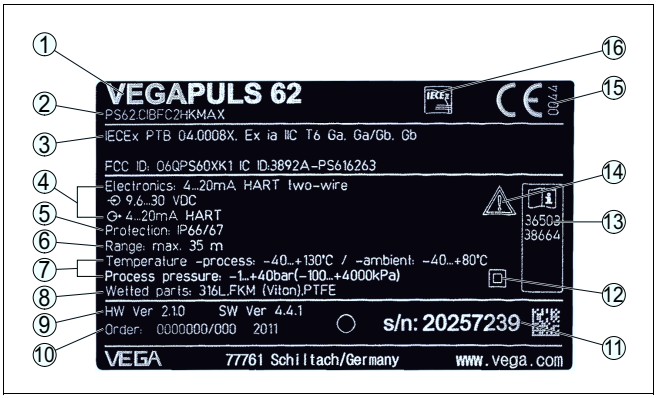

Fig. 1: Structure of the type label (example)

1 *Instrument type*
2 *Product code*
3 *Approvals*
4 *Power supply and signal output, electronics*
5 *Protection rating*
6 *Measuring range*
7 *Process and ambient temperature, process pressure*
8 *Material, wetted parts*
9 *Hardware and software version*
10 *Order number*
11 *Serial number of the instrument*
12 *Symbol of the device protection class*
13 *ID numbers, instrument documentation*
14 *Note to observe the instrument documentation*
15 *Notified authority for CE marking*
16 *Approval directive*

Serial number

With the serial number of the instrument on the type label you have access to the following data on our homepage:

- Article number of the instrument (HTML)
- Delivery date (HTML)
- Order-specific instrument features (HTML)
- Operating instructions at the time of shipment (PDF)
- Order-specific sensor data for an electronics exchange (XML)
- Test certificate "Measuring Accuracy" (PDF)

Go to www.vega.com, "*Service*" "*VEGA Tools*" and "*serial number search*".

Scope of the operating instructions manual

This operating instructions manual applies to the following instrument versions:

- Hardware from 2.1.1
- Software from 4.4.0

Scope of delivery

The scope of delivery encompasses:

- Radar sensor
- Documentation
  - this operating instructions manual
  - Test certificate Measurement accuracy, depending on the instrument VEGAPULS 65 (optional)
  - Operating instructions manual "*Indicating and adjustment module*" (optional)
  - Ex-specific "*Safety instructions*" (with Ex versions)
  - if necessary, further certificates

3.2 Principle of operation

Application area

The VEGAPULS 65 is a radar sensor for continuous measurement of liquids under simple process conditions. It is particularly suitable for level measurement in vessels with small process fittings and under simple process conditions.

The instrument can be used with products with an ε_r value ≥1.8. The actually achievable value depends on the measuring conditions, the antenna system, the standpipe or bypass.

Functional principle

The antenna of the radar sensor emits short radar pulses with a duration of approx. 1 ns. These pulses are reflected by the product and received by the antenna as echoes. The transit time of the radar pulses from emission to reception is proportional to the distance and hence to the level. The determined level is converted into an appropriate output signal and outputted as measured value.

3.3 Packaging, transport and storage

Packaging

Your instrument was protected by packaging during transport. Its capacity to handle normal loads during transport is assured by a test according to DIN EN 24180.

The packaging of standard instruments consists of environment-friendly, recyclable cardboard. For special versions, PE foam or PE foil is also used. Dispose of the packaging material via specialised recycling companies.

Transport

Transport must be carried out under consideration of the notes on the transport packaging. Nonobservance of these instructions can cause damage to the device.

Transport inspection

The delivery must be checked for completeness and possible transit damage immediately at receipt. Ascertained transit damage or concealed defects must be appropriately dealt with.

Storage

Up to the time of installation, the packages must be left closed and stored according to the orientation and storage markings on the outside.

Unless otherwise indicated, the packages must be stored only under the following conditions:

- Not in the open
- Dry and dust free
- Not exposed to corrosive media
- Protected against solar radiation
- Avoiding mechanical shock and vibration

Storage and transport temperature

- Storage and transport temperature see chapter "*Supplement - Technical data - Ambient conditions*"
- Relative humidity 20 … 85 %

3.4 Accessories and replacement parts

Indicating and adjustment module

The indicating and adjustment module PLICSCOM is used for measured value indication, adjustment and diagnosis. It can be inserted into the sensor and removed at any time.

You can find further information in the operating instructions "*Indicating and adjustment module PLICSCOM*" (Document-ID 27835).

Interface adapter

The interface adapter VEGACONNECT enables the connection of communication-capable instruments to the USB interface of a PC. For parameter adjustment of these instruments, an adjustment software such as PACTware with VEGA-DTM is required.

You can find further information in the operating instructions "*Interface adapter VEGACONNECT*" (Document-ID 32628).

External indicating and adjustment unit

VEGADIS 61 is an external indicating and adjustment unit for sensors with single chamber housing and Ex-d double chamber housing.

It is suitable for measured value indication and adjustment of plics® sensors and is connected to the sensor with a four-wire, screened standard cable up to 50 m long.

You can find further information in the operating instructions "*VEGADIS 61*" (Document-ID 27720).

External indicating and adjustment unit with HART protocol

VEGADIS 62 is suitable for measured value indication and adjustment of sensors with HART protocol. It is looped into the 4 … 20 mA/HART signal cable.

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You can find further information in the operating instructions "*VEGADIS 62*" (Document-ID 36469).

External radio unit

The PLICSMOBILE T61 is an external GSM/GPRS radio unit for transmission of measured values and for remote parameter adjustment of plics® sensors. The adjustment is carried out via PACTware/DTM by using the integrated USB connection.

You can find further information in the supplementary instructions "*PLICSMOBILE T61*" (Document-ID 36849).

Protective cover

The protective cover protects the sensor housing against soiling and intense heat from solar radiation.

You will find additional information in the supplementary instructions manual "*Protective cover*" (Document-ID 34296).

Flanges

Flanges are available in different versions according to the following standards: DIN 2501, EN 1092-1, ANSI B 16.5, JIS B 2210-1984, GOST 12821-80.

You can find additional information in the supplementary instructions manual "*Flanges according to DIN-EN-ASME-JIS*" (Document-ID 31088).

Electronics module

The electronics module VEGAPULS series 60 is a replacement part for radar sensors of VEGAPULS series 60. There is a different version available for each type of signal output.

You can find further information in the operating instructions "*Electronics module VEGAPULS series 60*" (Document-ID 36801).

4 Mounting

4.1 General instructions

Screwing in

With instruments with threaded process fitting, suitable tools must be applied for tightening the hexagon.

Warning:
The housing must not be used to screw the instrument in! Applying tightening force can damage internal parts of the housing.

Moisture

Use the recommended cables (see chapter "*Connecting to power supply*") and tighten the cable gland.

You can give your instrument additional protection against moisture penetration by leading the connection cable downward in front of the cable entry. Rain and condensation water can thus drain off. This applies mainly to outdoor mounting as well as installation in areas where high humidity is expected (e.g. through cleaning processes) or on cooled or heated vessels.

Suitability for the process conditions

Make sure that all parts of the instrument exposed to the process, in particular the active measuring component, process seal and process fitting, are suitable for the existing process conditions. These include above all the process pressure, process temperature as well as the chemical properties of the medium.

You can find the specifications in chapter "*Technical data*" and on the type label.

4.2 Instructions for installation

Sealing of the encapsulated antenna system

The flange screws must be tightened so that the PTFE washer of the encapsulated antenna system seals effectively. You can find the required torque in the technical data.

You can counteract the material-induced tension loss with PTFE by doing the following:

1. Make sure the number of flange screws corresponds to the number of flange holes
2. Use disc springs in addition to the flange screws for fastening the flange
3. Tighten all screws with the torque stated in the technical data

Polarisation plane

The emitted radar impulses of the radar sensor are electromagnetic waves. The polarisation plane is the direction of the electrical wave component. By turning the instrument in the connection flange or mounting boss, the polarisation can be used to reduce the effects of false echoes.

The position of the polarisation plane is marked on the process fitting of the instrument.

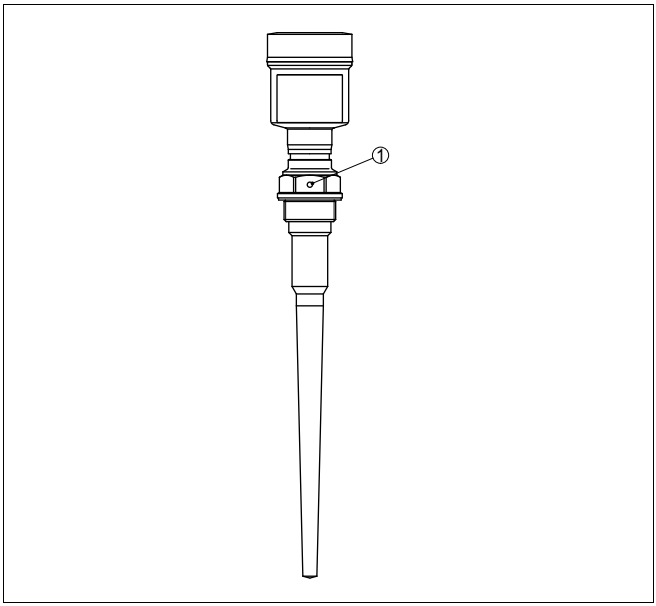

Fig. 2: Position of the polarisation plane of VEGAPULS 65

1 Marking hole

Mounting position

When mounting the VEGAPULS 65, keep a distance of at least 500 mm (19.69 in) to the vessel wall. If the sensor is installed in the center of dished or round vessel tops, multiple echoes can arise. These can, however, be suppressed by an appropriate adjustment (see chapter "*Setup*").

If you cannot keep this distance you should carry out a false echo storage before setup. This applies mainly if buildup on the vessel wall is expected. In this case, we recommend repeating a false echo storage later with existing buildup.

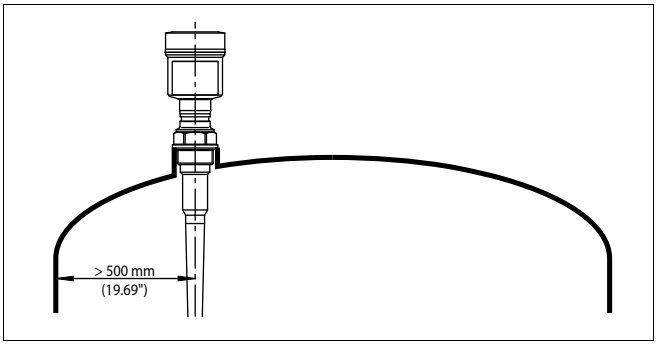

Fig. 3: Mounting of the radar sensor on round vessel tops

In vessels with conical bottom it can be advantageous to mount the sensor in the center of the vessel, as measurement is then possible down to the lowest point of the vessel bottom.

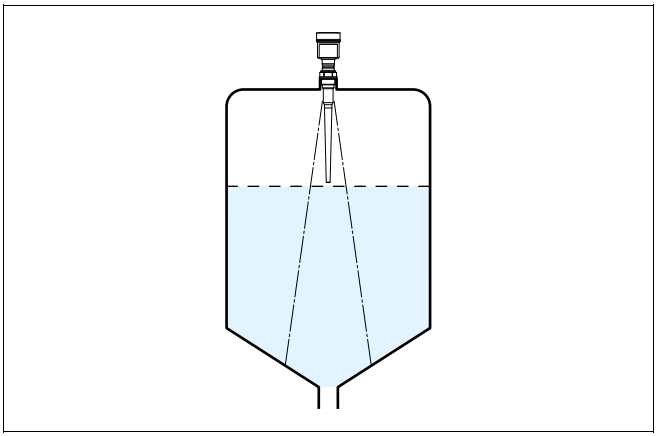

Fig. 4: Mounting of the radar sensor on vessels with conical bottom

Inflowing medium

Do not mount the instruments in or above the filling stream. Make sure that you detect the product surface, not the inflowing product.

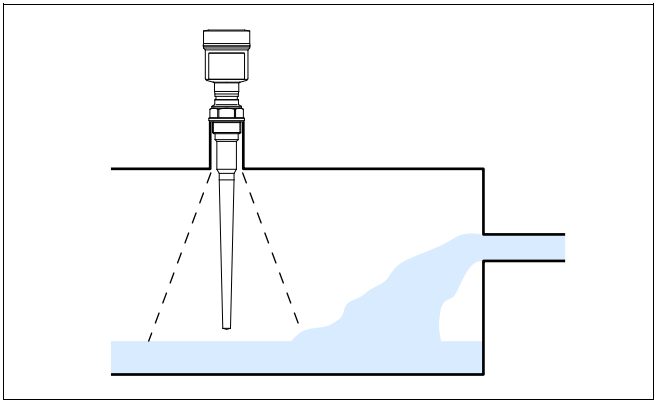

Fig. 5: Mounting of the radar sensor with inflowing medium

Socket

The active part of the antenna, i.e. the conical antenna part should protrude completely out of the socket.

To meet the different socket dimensions, sensors for socket lengths up to 50, 100 and 250 mm (2, 4, 10 in) are available.

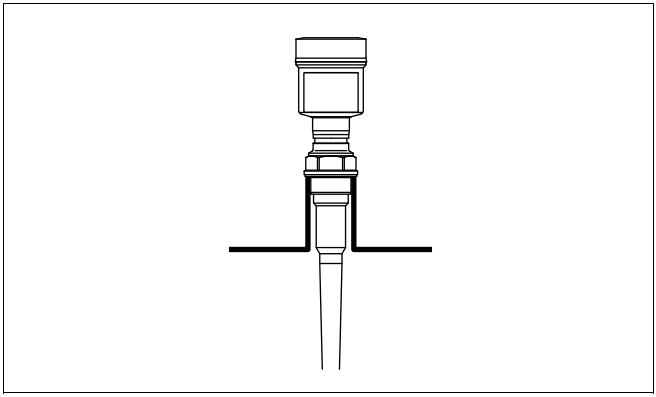

Fig. 6: Recommended socket mounting

In case of very big socket diameters, the active antenna part can be slightly recessed in the socket. The following rule applies to the standard version of VEGAPULS 65: Socket diameter corresponds to max. socket height.

Sensor orientation

Align the sensor in liquids as vertical as possible to the product surface to achieve optimum measurement results.

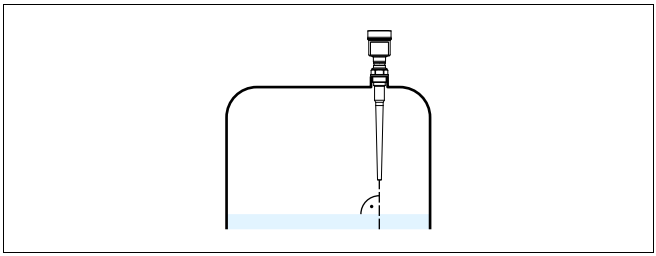

Fig. 7: Alignment in liquids

Vessel installations

The mounting location of the radar sensor should be a place where no other equipment or fixtures cross the path of the microwave signals.

Vessel installations, such as e.g. ladders, limit switches, heating spirals, struts, etc., can cause false echoes and impair the useful echo. Make sure when planning your measuring site that the radar sensor has a "clear view" to the measured product.

In case of existing vessel installations, a false echo storage should be carried out during setup.

If large vessel installations such as struts or supports cause false echoes, these can be attenuated through supplementary measures. Small, inclined sheet metal baffles above the installations scatter the radar signals and prevent direct interfering reflections.

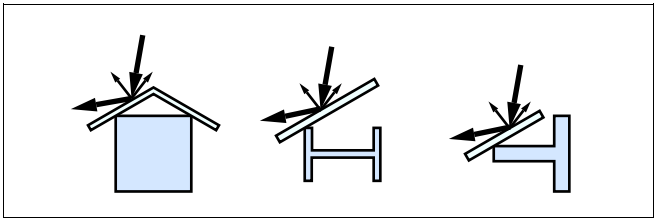

Fig. 8: Cover smooth profiles with deflectors

Agitators

If there are agitators in the vessel, a false signal memory should be carried out with the agitators in motion. This ensures that the interfering reflections from the agitators are saved with the blades in different positions.

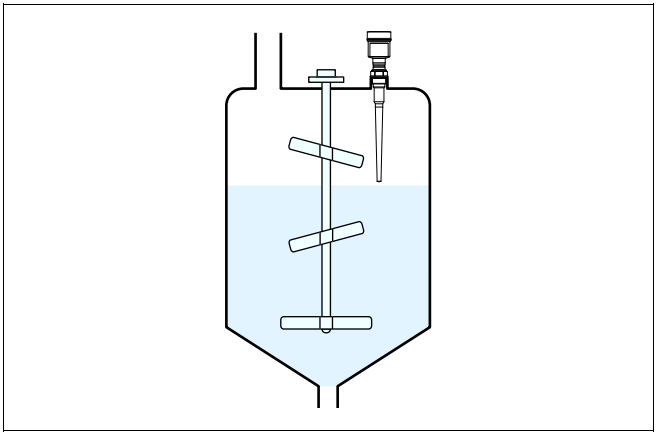

Fig. 9: Agitators

Foam generation

Through the action of filling, stirring and other processes in the vessel, dense foams which considerably damp the emitted signals may form on the product surface.

If foams are causing measurement errors, the biggest possible radar antenna should be used.

As an alternative, sensors with guided microwave can be used. These are unaffected by foam generation and are best suited for such applications.

5 Connecting to power supply

5.1 Preparing the connection

Safety instructions

Always keep in mind the following safety instructions:

- Connect only in the complete absence of line voltage
- If voltage surges are expected, install overvoltage arresters

Voltage supply via mains voltage

In this case, the instrument is designed in protection class II. To maintain this protection class, it is absolutely necessary that the ground conductor be connected to the internal ground terminal. Take note of the general installation regulations.

Supply voltage and current output are carried on separate connection cables if reliable separation is required. The supply voltage range can differ depending on the instrument version.

The data for power supply are specified in chapter "*Technical data*".

Select connection cable

An approved, three-wire installation cable with PE conductor is required for voltage supply with mains voltage.

The 4 … 20 mA current output is connected with standard two-wire cable without screen. If electromagnetic interference is expected which is above the test values of EN 61326-1 for industrial areas, screened cable should be used.

Use cable with round cross-section. A cable outer diameter of 5 … 9 mm (0.2 … 0.35 in) ensures the seal effect of the cable gland. If you are using cable with a different diameter or cross-section, exchange the seal or use a suitable cable gland.

Cable gland ½ NPT

With plastic housing, the NPT cable gland or the Conduit steel tube must be screwed without grease into the threaded insert.

Max. torque for all housings see chapter "*Technical data*"

Cable screening and grounding

If screened cable is necessary, connect the cable screen on both ends to ground potential. In the sensor, the screen must be connected directly to the internal ground terminal. The ground terminal on the outside of the housing must be connected to the potential equalisation (low impedance).

If potential equalisation currents are expected, the connection on the processing side must be made via a ceramic capacitor (e. g. 1 nF, 1500 V). The low frequency potential equalisation currents are thus suppressed, but the protective effect against high frequency interference signals remains.

Warning:
Significant potential differences exist inside galvanization plants as well as on vessels with cathodic corrosion protection. Considerable equalisation currents can flow over the cable screen if the screen is grounded on both ends.

To avoid this in such applications, the cable screen must be connected to ground potential only at one end (in the switching cabinet). The cable screen must **not** be connected to the internal ground terminal in the sensor and the outer ground terminal on the housing must **not** be connected to the potential equalisation!

Information:
The metal parts of the instrument (antenna, transmitter, concentric tube, etc.) are conductive connected with the inner and outer ground terminal on the housing. This connection exists either directly metallic or with instruments with external electronics via the screen of the special connection cable.

You can find specifications to the potential connections within the instrument in chapter "*Technical data*".

5.2 Connecting

Connection technology

The voltage supply and signal output are connected via the spring-loaded terminals in the housing.

The connection to the indicating and adjustment module or to the interface adapter is carried out via contact pins in the housing.

Connection procedure

Proceed as follows:

1 Unscrew the housing cover
2 If an indicating and adjustment module is installed, remove it by turning it slightly to the left.
3 Loosen compression nut of the cable entry
4 Remove approx. 10 cm (4 in) of the cable mantle, strip approx. 1 cm (0.4 in) of insulation from the ends of the individual wires

5 Insert the cable into the sensor through the cable entry

Fig. 10: Connection steps 5 and 6

6 Insert the wire ends into the terminals according to the wiring plan

Information:
Solid cores as well as flexible cores with cable end sleeves are inserted directly into the terminal openings. In case of flexible cores without end sleeves, press the terminal head with a small screwdriver; the terminal opening is freed. When the screwdriver is released, the terminal closes again.

7 Check the hold of the wires in the terminals by lightly pulling on them

8 Connect the screen to the internal ground terminal, connect the outer ground terminal to potential equalisation

9 Tighten the compression nut of the cable entry. The seal ring must completely encircle the cable

10 Screw the housing cover back on

The electrical connection is finished.

Information:
The terminal block is pluggable and can be removed from the electronics. To do this, lift the terminal block with a small screwdriver and pull it out. When inserting the terminal block again, you should hear it snap in.

5.3 Wiring plan, double chamber housing

The following illustrations apply to the non-Ex as well as to the Ex-d version.

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Electronics compartment

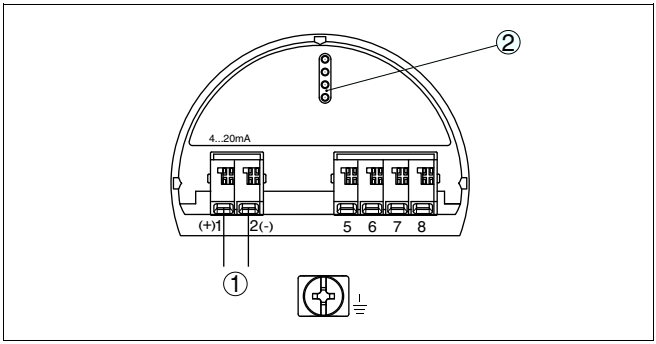


Fig. 11: Electronics compartment, double chamber housing

1 Internal connection to the connection compartment
2 For indicating and adjustment module or interface adapter

Information:
The connection of an external indicating and adjustment unit is not possible with this double chamber housing.

Connection compartment with mains voltage

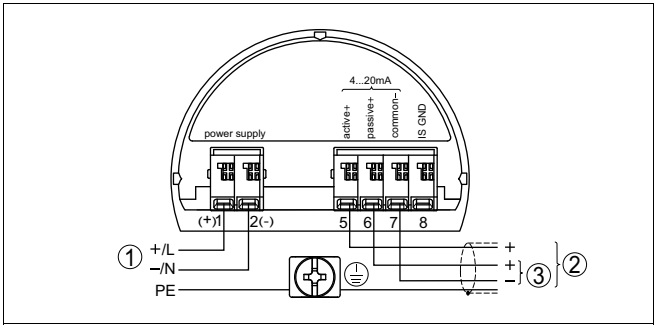


Fig. 12: Connection compartment with double chamber housing with mains voltage

1 Voltage supply
2 4 … 20 mA signal output active
3 4 … 20 mA signal output passive

Connection compartment with low voltage

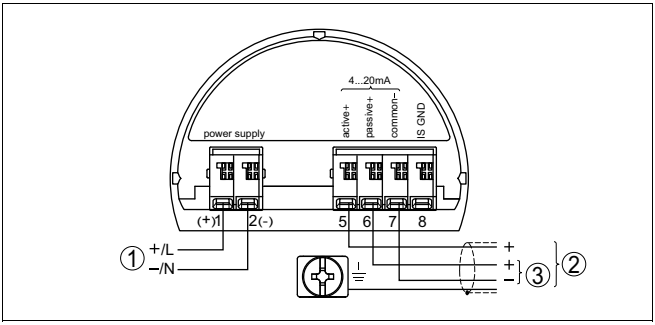


Fig. 13: Connection compartment with double chamber housing with low voltage

1 Voltage supply
2 4 … 20 mA signal output active
3 4 … 20 mA signal output passive

5.4 Switch on phase

After connecting the instrument to power supply or after a voltage recurrence, the instrument carries out a self-check for approx. 30 s:

- Internal check of the electronics
- Indication of the instrument type, hardware and software version, measurement loop name on the display or PC
- Indication of the status message "*F 105 Determine measured value*" on the display or PC
- The output signal jumps to the set error current

As soon as a plausible measured value is found, the corresponding current is outputted to the signal cable. The value corresponds to the actual level as well as the settings already carried out, e.g. factory setting.

6 Set up with the indicating and adjustment module

6.1 Insert indicating and adjustment module

The indicating and adjustment module can be inserted into the sensor and removed any time. Four positions displaced by 90° can be selected. It is not necessary to interrupt the power supply.

Proceed as follows:

1 Unscrew the housing cover

2 Place the indicating and adjustment module in the requested position onto the electronics and turn to the right until it snaps in

3 Screw housing cover with inspection window tightly back on

Removal is carried out in reverse order.

The indicating and adjustment module is powered by the sensor, an additional connection is not necessary.

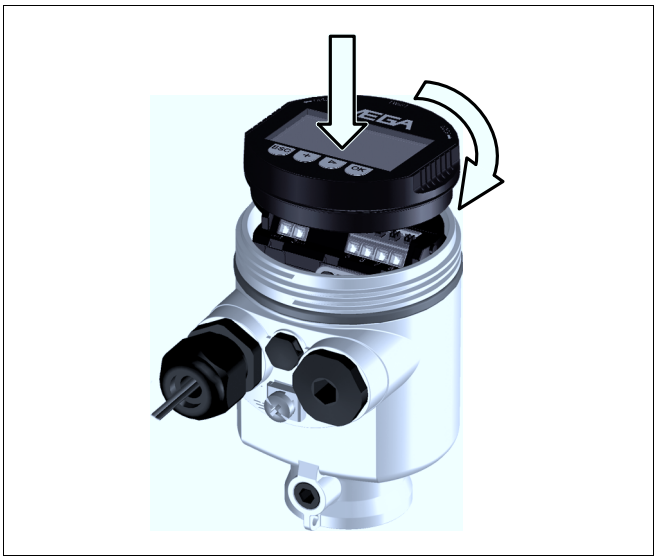


Fig. 14: Insertion of the indicating and adjustment module with single chamber housing into the electronics compartment

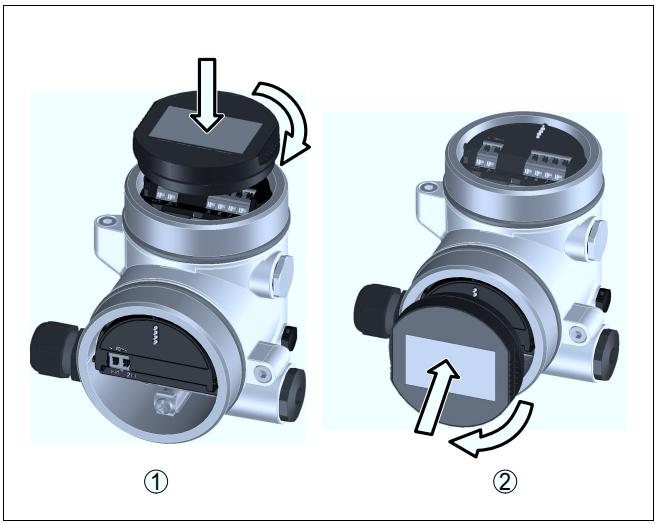


Fig. 15: Insertion of the indicating and adjustment module with double chamber housing

1 In the electronics compartment
2 In the connection compartment (with Ex d version not possible)

Note:
If you intend to retrofit the instrument with an indicating and adjustment module for continuous measured value indication, a higher cover with an inspection glass is required.

6.2 Adjustment system

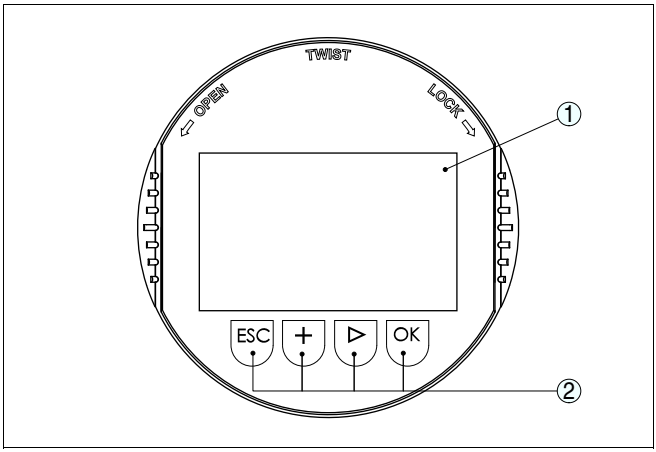


Fig. 16: Indicating and adjustment elements

1 LC display
2 Adjustment keys

Key functions

- ***[OK]*** key:
  - Move to the menu overview
  - Confirm selected menu
  - Edit parameter
  - Save value
- ***[->]*** key:
  - Presentation change measured value
  - Select list entry
  - Select editing position
- ***[+]*** key:
  - Change value of the parameter
- ***[ESC]*** key:
  - interrupt input
  - Return to higher-ranking menu

Adjustment system

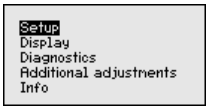
The sensor is adjusted via the four keys of the indicating and adjustment module. The LC display indicates the individual menu items. The functions of the individual keys are shown in the above illustration. Approx. 10 minutes after the last pressing of a key, an automatic reset to measured value indication is triggered. Any values not confirmed with ***[OK]*** will not be saved.

6.3 Parameter adjustment

Through the parameter adjustment the instrument is adapted to the application conditions. The parameter adjustment is carried out via an adjustment menu.

Main menu

The main menu is divided into five sections with the following functions:



Setup: Settings, e.g., for measurement loop name, medium, application, vessel, adjustment, signal output

Display: Settings, e.g., for language, measured value display, lighting

Diagnosis: Information, e.g. on the instrument status, pointer, reliability, simulation, echo curve

Further settings: Instrument unit, false signal suppression, linearisation curve, reset, date/time, reset, copy function

Info: Instrument name, hardware and software version, calibration date, instrument features

Information:
In this operating instructions manual, the instrument-specific parameters in the menu sections "*Setup*", "*Diagnosis*" and "*Additional settings*" are described. The general parameters in these menu section are described in the operating instructions manual "*Indicating and adjustment module*".

You can find in the operating instructions manual "*Indicating and adjustment module*" also the description of the menu sections "*Display*" and "*Info*".

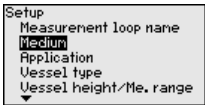
In the main menu point "*Setup*", the individual submenu points should be selected subsequently and provided with the correct parameters to ensure the optimum adjustment of the measurement. The procedure is described in the following.

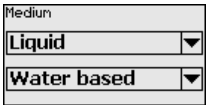
Setup

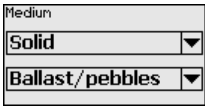
Setup/Medium

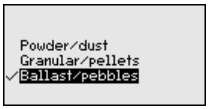
Each medium has different reflection properties. With liquids, further interfering factors are fluctuation product surface and foam generation. With bulk solids, these are dust generation, material cone and additional echoes from the vessel wall.

To adapt the sensor to these different measuring conditions, the selection "*Liquid*" or "*Bulk solid*" should be made in this menu item.









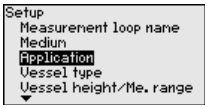
Through this selection, the sensor is adapted perfectly to the product and measurement reliability, particularly in products with poor reflective properties, is considerably increased.

Enter the requested parameters via the appropriate keys, save your settings with ***[OK]*** and jump to the next menu item with the ***[ESC]*** and the ***[->]*** key.

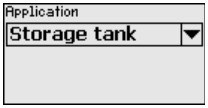
Setup/Application

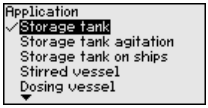
In addition to the medium, also the application, i.e. the measuring site, can influence the measurement.

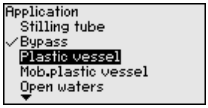
With this menu item, the sensor can be adapted to the applications. The adjustment possibilities depend on the selection "*Liquid*" or "*Bulk solid*" under "*Medium*".

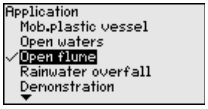


The following options are available when "*Liquid*" is selected:

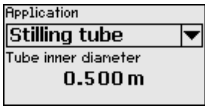


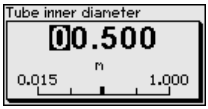






The selection "*Standpipe*" opens a new window in which the inner diameter of the applied standpipe is entered.





The following features form the basis of the applications:

Storage tank:

- Setup: large-volumed, upright cylindrical, spherical

- Product speed: slow filling and emptying
- Process/measurement conditions:
  - Condensation
  - Smooth product surface
  - Max. requirement to the measurement accuracy

Storage tanke with product circulation:

- Setup: large-volumed, upright cylindrical, spherical
- Product speed: slow filling and emptying
- Vessel: small laterally mounted or large top mounted stirrer
- Process/measurement conditions:
  - Relatively smooth product surface
  - Max. requirement to the measurement accuracy
  - Condensation
  - Slight foam generation
  - Overfilling possible

Storage tank on ships (Cargo Tank):

- Product speed: slow filling and emptying
- Vessel:
  - Installations in the bottom section (bracers, heating spirals)
  - High sockets 200 … 500 mm, also with large diameters
- Process/measurement conditions:
  - Condensation, buildup by movement
  - Max. requirement on measurement accuracy from 95 %

Stirrer vessel (reactor):

- Setup: all vessel sizes possible
- Product speed:
  - Fast to slow filling possible
  - Vessel is very often filled and emptied
- Vessel:
  - Socket available
  - Large agitator blades of metal
  - Vortex breakers, heating spirals
- Process/measurement conditions:
  - Condensation, buildup by movement
  - Strong spout generation
  - Very agitated surface, foam generation

Dosing vessel:

- Setup: all vessel sizes possible
- Product speed:
  - Fast filling and emptying
  - Vessel is very often filled and emptied
- Vessel: narrow installation situation
- Process/measurement conditions:
  - Condensation, buildup on the antenna
  - Foam generation

Standpipe:

- Product speed: very fast filling and emptying
- Vessel:
  - Vent hole
  - Joins like flanges, weld joints
  - Shifting of the running time in the tube
- Process/measurement conditions:
  - Condensation
  - Buildup

Bypass:

- Product speed:
  - Fast up to slow filling with short up to long bypass tube possible
  - Often the level is hold via a control facility
- Vessel:
  - Lateral outlets and inlets
  - Joins like flanges, weld joints
  - Shifting of the running time in the tube
- Process/measurement conditions:
  - Condensation
  - Buildup
  - Separation of oil and water possible
  - Overfilling into the antenna possible

Plastic tank:

- Vessel:
  - Measurement fix mounted or integrated
  - Measurement depending on the application through the vessel top
  - With empty vessel, the measurement can be carried out through the bottom
- Process/measurement conditions:
  - Condensation on the plastic ceiling
  - In outside facilities water and snow on the vessel top possible

Transportable plastic tank:

- Vessel:
  - Material and thickness different
  - Measurement through the vessel top
- Process/measurement conditions:
  - Measured value jump with vessel change

Open water (gauge measurement):

- Gauge rate of change: slow gauge change
- Process/measurement conditions:
  - Distance sensor to water surface to big
  - Extreme damping of output signal due to wave generation

- Ice and condensation on the antenna possible
- Spiders and insect nestle in the antennas
- Floating material and animals sporadically on the water surface

Open flume (flow measurement):

- Gauge rate of change: slow gauge change
- Process/measurement conditions:
  - Ice and condensation on the antenna possible
  - Spiders and insect nestle in the antennas
  - Smooth water surface
  - Exact measurement result required
  - Distance to the water surface normally relatively high

Rain water overfall (weir):

- Gauge rate of change: slow gauge change
- Process/measurement conditions:
  - Ice and condensation on the antenna possible
  - Spiders and insect nestle in the antennas
  - Turbulent water surface
  - Sensor flooding possible

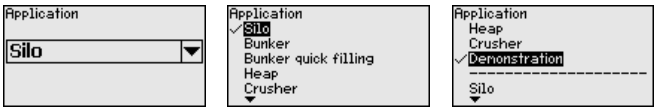
Demonstration:

- Adjustment for all applications which are not typically level measurement
- Sensor accepts all measured value changes within the measuring range immediately
- Typical applications:
  - Instrument demonstration
  - Object recognition/monitoring (additional settings required)

Caution:
If a separation of liquids with different dielectric figure occurs in the vessel, for example through condensation, the radar sensor can detect under certain circumstances only the medium with the higher dielectric figure. Keep in mind that layer interfaces can cause faulty measurements.

If you want to measure the total height of both liquids reliably, please contact our service department or use an instrument specially designed for interface measurement.

The following options are available when "*Bulk solid*" is selected:



The following features form the basis of the applications:

Silo (slim and high):

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- Vessel of metal: weld joints
- Process/measurement conditions:
  - Filling too close to the sensor
  - System noise with completely empty silo increased
  - Automatic false signal suppression with partly filled vessel

Bunker (large-volumed):

- Vessel of concrete or metal:
  - Structured vessel walls
  - Installations present
- Process/measurement conditions:
  - Large distance to the medium
  - Large angles of repose

Bunker with fast filling:

- Vessel of concrete or metal, also multiple chamber silo:
  - Structured vessel walls
  - Installations present
- Process/measurement conditions:
  - Measured value jumps, e.g. by truck loading
  - Large distance to the medium
  - Large angles of repose

Heap:

- Sensor mounting on movable conveyor belts
- Detection of the heap profile
- Height detection during filling
- Process/measurement conditions:
  - Measured value jumps, e.g. by the profile of the heap or traverses
  - Large angles of repose
  - Measurement near the filling stream

Crusher:

- Vessel: installations, wear and protective facilities available
- Process/measurement conditions:
  - Measured value jumps, e.g. by truck loading
  - Fast reaction time
  - Large distance to the medium

Demonstration:

- Adjustment for all applications which are not typically level measurement
- Sensor accepts all measured value changes within the measuring range immediately
- Typical applications:
  - Instrument demonstration
  - Object recognition/monitoring (additional settings required)

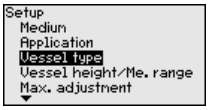
Through this selection, the sensor is adapted optimally to the application or the location and measurement reliability under the various basic conditions is increased considerably.

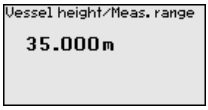
Enter the requested parameters via the appropriate keys, save your settings with ***[OK]*** and jump to the next menu item with the ***[ESC]*** and the ***[->]*** key.

Setup/Vessel height, measuring range

With this selection, the operating range of the sensor is adapted to the vessel height and the reliability with different frame conditions is increased considerably.

Independent from this, the min. adjustment must be carried out.

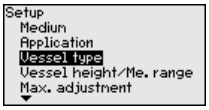


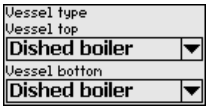


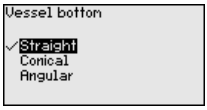
Enter the requested parameters via the appropriate keys, save your settings with ***[OK]*** and jump to the next menu item with the ***[ESC]*** and the ***[->]*** key.

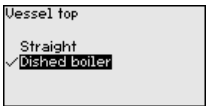
Setup/Vessel form

Also the vessel form can influence the measurement apart from the medium and the application. To adapt the sensor to these measurement conditions, this menu item offers you different options for vessel bottom and ceiling in case of certain applications.









Enter the requested parameters via the appropriate keys, save your settings with ***[OK]*** and jump to the next menu item with the ***[ESC]*** and the ***[->]*** key.

Setup/Adjustment

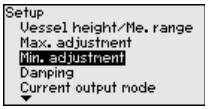
Because a radar sensor is a distance measuring instrument, the distance from the sensor to the product surface is measured. To have the real product level displayed, an allocation of the measured distance to the percentage height must be made. To carry out this adjustment, the distance is entered with full and empty vessel. If these values are not known, an adjustment with the distance values, e.g. 10 % and 90 % is also possible. Starting point for these distance specifications is always the seal surface of the thread or flange. By means of these settings, the real level is calculated.

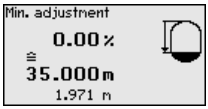
The real product level during this adjustment is not important, because the min./max. adjustment is always carried out without changing the product level. These settings can be made ahead of time without the instrument having to be installed.

Setup/Min. adjustment

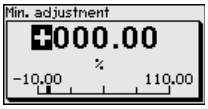
Proceed as follows:

1 Select the menu item "*Setup*" with ***[->]*** and confirm with ***[OK]***. Now select with ***[->]*** the menu item "*Min. adjustment*" and confirm with ***[OK]***.

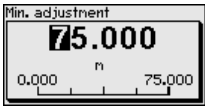




2 Edit the percentage value with ***[OK]*** and set the cursor to the requested position with ***[->]***.



3 Set the requested percentage value with ***[+]*** and save with ***[OK]***. The cursor jumps now to the distance value.



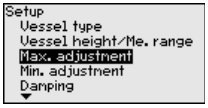
4 Enter the suitable distance value in m for the empty vessel (e.g. distance from the sensor to the vessel bottom) corresponding to the percentage value.

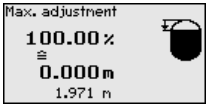
5 Save settings with ***[OK]*** and move with ***[ESC]*** and ***[->]*** to the max. adjustment.

Setup/Max. adjustment

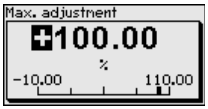
Proceed as follows:

1 Select with ***[->]*** the menu item max. adjustment and confirm with ***[OK]***.

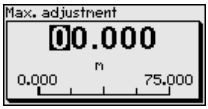




2 Prepare the percentage value for editing with ***[OK]*** and set the cursor to the requested position with ***[->]***.



3 Set the requested percentage value with ***[+]*** and save with ***[OK]***. The cursor jumps now to the distance value.

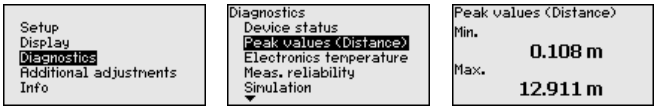


4 Enter the appropriate distance value in m (corresponding to the percentage value) for the full vessel. Keep in mind that the max. level must lie below the min. distance to the antenna edge.

5 Save settings with ***[OK]***

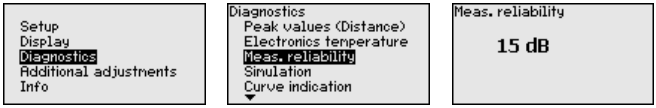
Diagnosis/Peak value

The respective min. and max. measured value is saved in the sensor. The values are displayed in the menu item "*Peak values*".



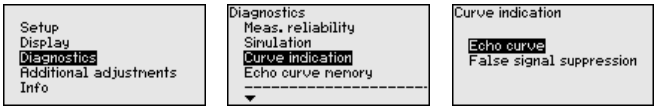
Diagnosis/Measurement reliability

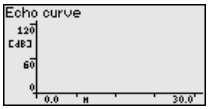
When non-contact level sensors are used, the measurement can be influenced by the respective process conditions. In this menu item, the measurement reliability of the level echo is displayed as dB value. The measurement reliability equals signal strength minus noise. The higher the value, the more reliable the measurement. With a functioning measurement, the values are > 10 dB.



Diagnoses/Curve indication

The "*Echo curve*" shows the signal strength of the echoes over the measuring range in dB. The signal strength enables an evaluation of the quality of the measurement.





The "*False signal suppression*" displays the saved false echoes (see menu "*Additional settings*") of the empty vessel with signal strength in "dB" over the measuring range.

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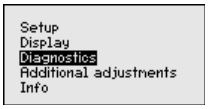
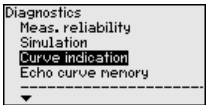
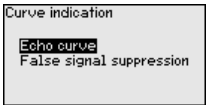
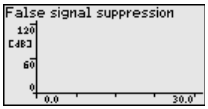








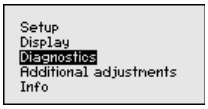
A comparison of echo curve and false signal suppression allows a more accurate conclusion on measurement reliability. The selected curve is continuously updated. With the ***[OK]*** key, a submenu with zoom functions is opened:

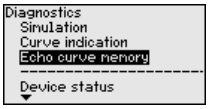
- "X-Zoom": Zoom function for the meas. distance
- "Y-Zoom": 1, 2, 5 and 10x signal magnification in "*dB*"
- "Unzoom": Reset the presentation to the nominal measuring range with single magnification

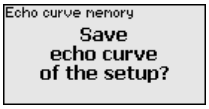
Diagnosis/Echo curve memory

With the function "*Echo curve memory*" the echo curve can be saved at the time of setup. This is generally recommended; for using the Asset Management functions it is absolutely necessary. If possible, the curve should be saved with a low level in the vessel.

With the adjustment software PACTware and the PC, the high resolution echo curve can be displayed and used to recognize signal changes over the operating time. In addition, the echo curve of the setup can be also displayed in the echo curve window and compared with the actual echo curve.







Further settings/False signal suppression

The following circumstances cause interfering reflections and can influence the measurement:

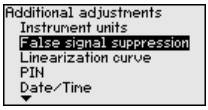
- High sockets
- Vessel installations such as struts
- Agitators
- Buildup or welded joints on vessel walls

Note:
A false signal suppression detects, marks and saves these false signals so that they are no longer taken into account for level measurement.

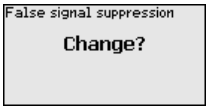
This should be done with a low level so that possible interfering reflections can be detected.

Proceed as follows:

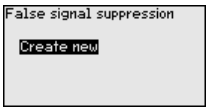
1 Select the menu item "*Additional settins*" with ***[->]*** and confirm with ***[OK]***. With ***[->]*** you have to select the menu item "*False signal suppression*" and confirm with ***[OK]***.



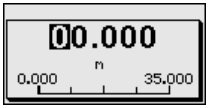
2 Confirm again with ***[OK]***.



3 Confirm again with ***[OK]***.



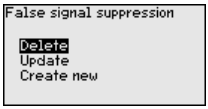
4 Confirm again with ***[OK]*** and enter the actual distance from the sensor to the product surface.



5 All interfering signals in this section are detected by the sensor and stored after confirming with ***[OK]***.

Note:
Check the distance to the product surface, because if an incorrect (too large) value is entered, the existing level will be saved as false signal. The filling level would then no longer be detectable in this area.

If a false signal suppression is already created in the sensor, then the following menu window appears when selecting "*False signal suppression*":

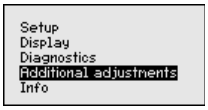


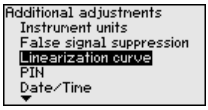
The menu item "*Delete*" is used to completely delete an already created false signal suppression. This is useful if the saved false signal suppression no longer matches the metrological conditions in the vessel.

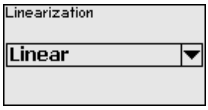
The menu item "*Extend*" is used to extend an already created false signal suppression. This is useful if a false signal suppression was carried out with a too high level and not all false signals could be detected. When selecting "*Extend*", the distance to the product surface of the created false signal suppression is displayed. This value can now be changed and the false signal suppression can be extended to this range.

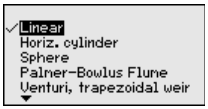
Further settings/Linearization curve

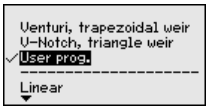
A linearisation is necessary for all vessels in which the vessel volume does not increase linearly with the level - e.g. in a horizontal cylindrical or spherical tank - and the indication or output of the volume is required. Corresponding linearisation curves are preprogrammed for these vessels. They represent the correlation between the level percentage and vessel volume. By activating the appropriate curve, the volume percentage of the vessel is displayed correctly. If the volume should not be displayed in percent but e.g. in l or kg, a scaling can be also set in the menu item "*Display*".







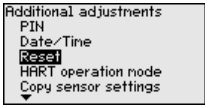


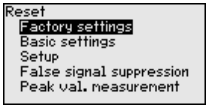


Enter the requested parameters via the appropriate keys, save your settings and jump to the next menu item with the ***[ESC]*** and ***[->]*** key.

Additional settings - Reset

With a reset, certain parameter adjustments carried out by the user are reset.





The following reset functions are available:

Delivery status: Restoring the parameter settings at the time of shipment from the factory incl. the order-specific settings. A created false signal suppression, user-programmable linearization curve as well as the measured value memory will be deleted.

Basic settings: Resetting the parameter settings incl. special and laboratory parameters to the default values of the respective instrument. A created false signal suppression, user programmable linearization curve as well as the measured value memory will be deleted.

Setup: Resetting of the parameter settings to the default values of the respective instrument in the menu item Setup. Order-related settings remain but are not taken over into the current parameters. User-generated false signal suppression, user-programmed linearization curve, measured value memory as well as event memory remain untouched. The linearization is set to linear.

False signal suppression: Deleting a previously created false signal suppression. The false signal suppression created in the factory remains active.

Peak values measured value: Resetting of the measured min. and max. distances to the actual measured value.

The following table shows the default values of the instrument. Depending on the instrument version, not all menu items are available or differently assigned:

Menu	Menu item	Default value
Setup	Measurement loop name	Sensor
	Medium	Liquid/Water Bulk solids/Crushed stones, gravel
	Application	Storage tank Silo
	Vessel form	Vessel bottom, dished boiler end Vessel top, dished boiler end
	Vesell height/ Measuring range	Recommended measuring range, see "*Technical data*" in the supplement
	Min. adjustment	Recommended measuring range, see "*Technical data*" in the supplement
	Max. adjustment	0,000 m(d)
	Damping	0.0 s
	Current output mode	4 … 20 mA, < 3.6 mA
	Current output Min./Max.	Min. current 3.8 mA, max. current 20.5 mA
	Lock operation	Released
Display	Language	Like order
	Displayed value	Distance
	Display unit	m
	Scaling size	Volume l

Menu	Menu item	Default value
	Scaling	0.00 lin %, 0 l 100.00 lin %, 100 l
	Lighting	Switched off
Further settings	Distance unit	m
	Temperature unit	°C
	Probe length	Length of the standpipe Ex factory
	Linearisation curve	linear
	HART mode	Standard Address 0

6.4 Saving the parameter adjustment data

We recommended noting the adjusted data, e.g. in this operating instructions manual, and archiving them afterwards. They are thus available for multiple use or service purposes.

If the instrument is equipped with an indicating and adjustment module, the data in the sensor can be saved in the indicating and adjustment module. The procedure is described in the operating instructions manual "*Indicating and adjustment module*" in the menu item "*Copy sensor data*". The data remain there permanently even if the sensor power supply fails.

The following data or settings for adjustment of the indicating and adjustment module are saved:

- All data of the menu "*Setup*" and "*Display*"
- In the menu "*Additional settings*" the items "*Sensor-specific units, temperature unit and linearization*"
- The values of the user programmable linearisation curve

The function can also be used to transfer settings from one instrument to another instrument of the same type. If it is necessary to exchange a sensor, the indicating and adjustment module is inserted into the replacement instrument and the data are likewise written into the sensor via the menu item "*Copy sensor data*".

7 Setup with PACTware

7.1 Connect the PC

Via the interface adapter directly on the sensor

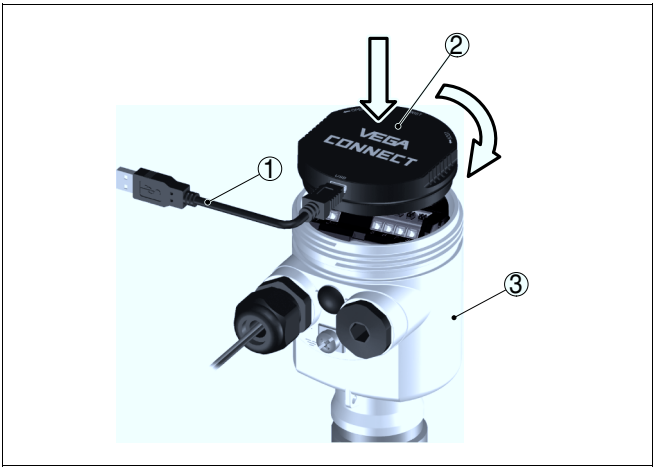


Fig. 17: Connection of the PC directly to the sensor via the interface adapter

1 USB cable to the PC
2 Interface adapter VEGACONNECT 4
3 Sensor

Information:
The interface adapter VEGACONNECT 3 is not suitable for connection to the sensor.

Connection via HART

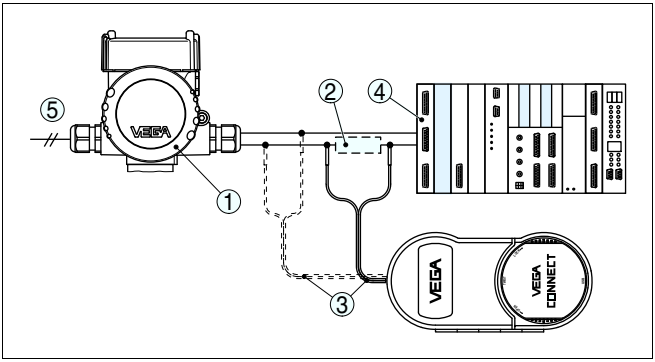


Fig. 18: Connecting the PC via HART to the signal cable

1 VEGAPULS 65
2 HART resistance 250 Ω (optional depending on processing)
3 Connection cable with 2 mm pins and terminals
4 Processing system/PLC/Voltage supply

Necessary components:

- VEGAPULS 65
- PC with PACTware and suitable VEGA DTM
- VEGACONNECT 4
- HART resistance approx. 250 Ω
- Power supply unit or processing system

Note:
With power supply units with integrated HART resistance (internal resistance approx. 250 Ω), an additional external resistance is not necessary. This applies, e.g. to the VEGA instruments VEGATRENN 149A, VEGAMET 381 and VEGAMET 391). Commercially available Ex separators are also usually equipped with sufficient current limitation resistance. In such cases, VEGACONNECT 4 can be connected parallel to the 4 … 20 mA cable.

7.2 Parameter adjustment with PACTware

Prerequisites

For parameter adjustment of the sensor via a Windows PC, the configuration software PACTware and a suitable instrument driver (DTM) according to FDT standard are required. The up-to-date PACTware version as well as all available DTMs are compiled in a DTM Collection. The DTMs can also be integrated into other frame applications according to FDT standard.

Note:
To ensure that all instrument functions are supported, you should always use the latest DTM Collection. Furthermore, not all described functions are included in older firmware versions. You can download the latest instrument software from our homepage. A description of the update procedure is also available in the Internet.

Further setup steps are described in the operating instructions manual "*DTM Collection/PACTware*" attached to each DTM Collection and which can also be downloaded from the Internet. Detailed descriptions are available in the online help of PACTware and the DTMs.

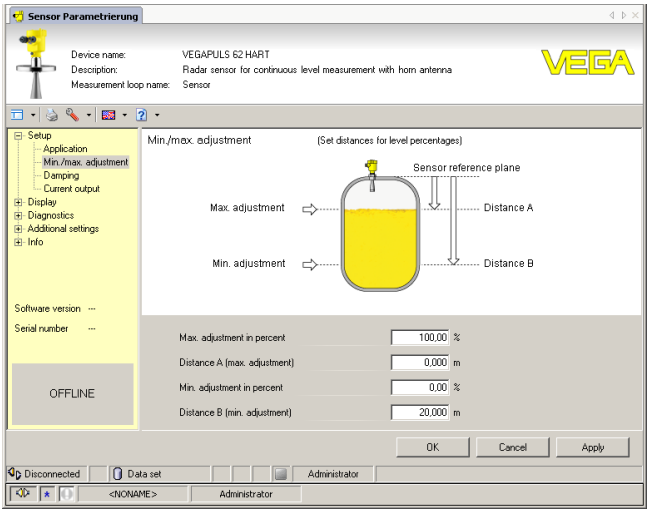


Fig. 19: Example of a DTM view

Standard/Full version

All device DTMs are available as a free-of-charge standard version and as a full version that must be purchased. In the standard version, all functions for complete setup are already included. An assistant for simple project configuration simplifies the adjustment considerably. Saving/printing the project as well as import/export functions are also part of the standard version.

In the full version there is also an extended print function for complete project documentation as well as a save function for measured value and echo curves. In addition, there is a tank calculation program as well as a multiviewer for display and analysis of the saved measured value and echo curves.

The standard version is available as a free-of-charge download under http://www.vega.com. The full version is available on CD from the agency serving you.

7.3 Saving the parameter adjustment data

We recommend documenting or saving the parameter adjustment data via PACTware. That way the data are available for multiple use or service purposes.

8 Set up with other systems

8.1 DD adjustment programs

Device descriptions as Enhanced Device Description (EDD) are available for DD adjustment programs such as, for example, AMS™ and PDM.

A free-of-charge download of these files is available via Internet. Move via www.vega.com and "*Downloads*" to "*Software*".

8.2 Communicator 375, 475

Device descriptions for the instrument are available as DD or EDD for parameter adjustment with the Field Communicator 375 or 475.

A free-of-charge download of these files is available via Internet. Move via www.vega.com and "*Downloads*" to "*Software*".

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9 Diagnosis, Asset Management and service

9.1 Maintenance

If the device is used correctly, no maintenance is required in normal operation.

9.2 Measured value and event memory

The instrument has several memories which are available for diagnosis purposes. The data remain even with voltage interruption.

Measured value memory

Up to 70,000 measured values can be stored in the sensor in a ring memory. Each entry contains date/time as well as the respective measured value.

Stored values are for example:

- Original sensor value
- Filling height
- Measured value
- Meas. reliability
- Electronics temperature

The requested values and recording conditions are set via a PC with PACTware/DTM or the control system with EDD. Data are thus read out and also reset.

Event memory

Up to 500 events are automatically stored with a time stamp in the sensor (non-deletable). Each entry contains date/time, event type, event description and value.

Event types are for example:

- Modification of a parameter
- Switching on and off times
- Status messages
- Error messages

The data are read out via a PC with PACTware/DTM or the control system with EDD.

Echo curve memory

The echo curves are stored with date and time and the corresponding echo data. The memory is divided into two sections:

Echo curve of the setup: This is used as reference echo curve for the measurement conditions during setup. Changes in the measurement conditions during operation or buildup on the antenna can thus be recognized.

The echo curve of setup is stored via:

- PC with PACTware/DTM
- Control system with EDD
- Indicating and adjustment module

Further echo curves: Up to 10 echo curves can be stored in a ring buffer in this memory section.

Additional echo curves are stored via:

- PC with PACTware/DTM
- Control system with EDD

9.3 Asset Management function

The instrument features self-monitoring and diagnosis according to NE 107 and VDI/VDE 2650. In addition to the status messages in the following tables there are more detailed error messages available under the menu item "*Diagnosis*" via the indicating and adjustment module, PACTware/DTM and EDD.

Status messages

The status messages are classified in the following categories:

- Failure
- Function check
- Out of specification
- Maintenance requirement

and explained by pictographs:

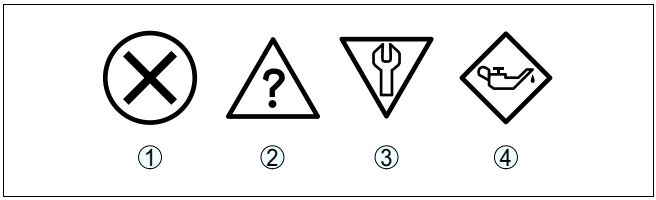


Fig. 20: Pictograms of the status messages

1 Failure - red
2 Function check - orange
3 Out of specification - yellow
4 Maintenance - blue

Failure: Due to a malfunction in the instrument, a failure message is outputted.

This status message is always active. It cannot be deactivated by the user.

Function check: The instrument is in operation, the measured value is temporarily invalid (for example during simulation).

This status message is always active. It cannot be deactivated by the user.

Out of specification: The measured value is unstable because the instrument specification is exceeded (e.g. electronics temperature).

This status message is inactive by default. It can be activated by the user via PACTware/DTM or EDD.

Maintenance: Due to external influences, the instrument function is limited. The measurement is affected, but the measured value is still valid. Plan in maintenance for the instrument because a failure is expected in the near future (e.g. due to buildup).

This status message is inactive by default. It can be activated by the user via PACTware/DTM or EDD.

Failure

The following table shows the error codes in the status message "*Failure*" and gives information on the reason and rectification. Keep in mind that some information is only valid with four-wire instruments.

Code Text message	Cause	Rectification
F013 no measured value available	• Sensor does not detect an echo during operation • Antenna system contaminated or defective	• Check or correct installation and/or parameter adjustment • Clean or exchange process component or antenna
F017 Adjustment span too small	• Adjustment not within specification	• Change adjustment according to the limit values (difference between min. and max. ≥ 10 mm)
F025 Error in the linearization table	• Index markers are not continuously rising, for examle unlogical value pairs	• Check linearization table • Delete table/Create new
F036 No operable software	• Failed or interrupted software update	• Repeat software update • Check electronics version • Exchange of the electronics • Send instrument for repair
F040 Error in the electronics	• Hardware defect	• Exchange of the electronics • Send instrument for repair
F080	• General software error	• Separate operating voltage briefly
F105 Determine measured value	• The instrument is still in the start phase, the measured value could not yet be determined	• Wait for the warm-up phase • Duration depending on the version and parameter adjustment up to approximately 3 min.
F113 Communication error	• EMC interferences • Transmission error with the external communication with 4-wire power supply unit	• Remove EMC influences • Exchange 4-wire power supply unit or electronics

Code Text message	Cause	Rectification
F125 Unpermissible electronics temperature	• Temperature of the electronics in the non-specified section	• Check ambient temperature • Isolate electronics • Use instrument with higher temperature range
F260 Error in the calibration	• Error in the calibration carried out in the factory • Error in the EEPROM	• Exchange of the electronics • Send instrument for repair
F261 Error in the configuration	• Error during setup • False signal suppression faulty • Error when carrying out a reset	• Repeat setup • Repeat reset
F264 Installation/Setup error	• Adjustment not within the vessel height/measuring range • Max. measuring range of the instrument not sufficient	• Check or correct installation and/or parameter adjustment • Use an instrument with bigger measuring range
F265 Measurement function disturbed	• Sensor does no longer carry out a measurement • Operating voltage too low	• Check operating voltage • Carry out a reset • Separate operating voltage briefly

Function check

The following table shows the error codes and text messages in the status message "*Function check*" and provides information on causes as well as corrective measures.

Code Text message	Cause	Rectification
C700 Simulation	• Simulation active	• Finish simulation • Wait for the automatic end after 60 mins.

Out of specification

The following table shows the error codes and text messages in the status message "*Out of specification*" and provides information on causes as well as corrective measures.

Code Text message	Cause	Rectification
S600 Unpermissible electronics temperature	• Temperature of the electronics in the non-specified section	• Check ambient temperature • Isolate electronics • Use instrument with higher temperature range
S601 Overfilling	• Danger of vessel overfilling	• Make sure that there is no further filling • Check level in the vessel

Maintenance

The following table shows the error codes and text messages in the status message "*Maintenance*" and provides information on causes as well as corrective measures.

Code Text message	Cause	Rectification
M500 Error with the reset delivery status	• With the reset to delivery status, the data could not be restored	• Repeat reset • Load XML file with sensor data into the sensor
M501 Error in the non-active linearization table	• Hardware error EEPROM	• Exchange of the electronics • Send instrument for repair
M502 Error in the diagnosis memory	• Hardware error EEPROM	• Exchange of the electronics • Send instrument for repair
M503 Reliability too low	• The echot/noise ratio is the small for a reliable measurement	• Check installation and process conditions • Clean the antenna • Change polarisation direction • Use instrument with higher sensitivity
M504 Error on an device interface	• Hardware defect	• Check connections • Exchange of the electronics • Send instrument for repair

Code Text message	Cause	Rectification
M505 No echo available	• Level echo can no longer be detected	• Clean the antenna • Use a more suitable antenna/sensor • Remove possible false echoes • Optimize sensor position and orientation

9.4 Remove interferences

Reaction when malfunctions occur

The operator of the system is responsible for taking suitable measures to rectify faults.

Procedure for fault rectification

The first measures are:

- Evaluation of fault messages via the indicating and adjustment module
- Checking the 4 … 20 mA signal
- Treatment of measurement errors

Further comprehensive diagnosis possibilities are offered by a PC with the software PACTware and suitable DTM.

In many case, the failure reasons can thus be determined and faults rectified.

Check the 4 … 20 mA signal

Connect a handmultimeter in the suitable measuring range according to the wiring plan. The following table describes possible errors in the current signal and helps to remove them:

Error	Cause	Rectification
4 … 20 mA signal not stable	• Level fluctuations	• Set damping according to the instrument via the indicating and adjustment module or PACTware/DTM
4 … 20 mA signal missing	• Electrical connection faulty	• Check connection according to chapter "Connection steps" and if necessary, correct according to chapter "Wiring plan".
	• Voltage supply missing	• Check cables for breaks; repair if necessary
	• Operating voltage too low or load resistance too high	• Check, adapt if necessary

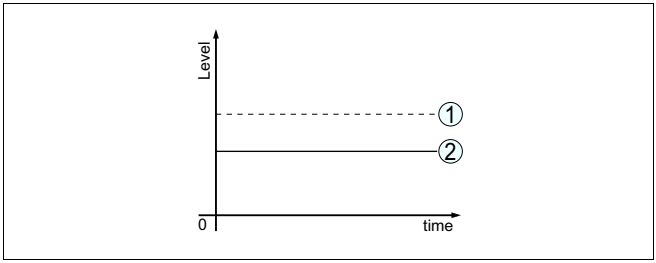
Error	Cause	Rectification
Current signal greater than 22 mA or less than 3.6 mA	• Electronics module in the sensor defective	• Exchange the instrument or send it in for repair

Treatment of measurement errors with liquids

The below tables show typical examples of application-relevant measurement errors with liquids. The measurement errors are differentiated according to the following:

- Constant level
- Filling
- Emptying

The images in column "*Error pattern*" show the actual level with a broken line and the level displayed by the sensor as a continuous line.

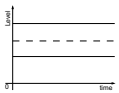


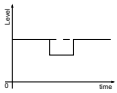
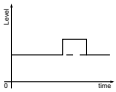
1 Real level
2 Level displayed by the sensor

Instructions:

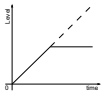
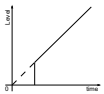
- Wherever the sensor displays a constant value, the reason could also be the fault setting of the current output to "Hold value"
- In case of a too low level indication, the reason could be a line resistance that is too high

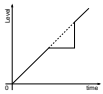
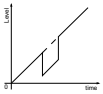
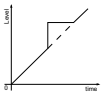
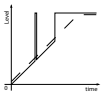
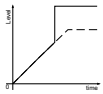
Measurement error with constant level

Fault description	Error pattern	Cause	Rectification
1. Measured value shows a too low or too high level		• Min./max. adjustment not correct	• Adapt min./max. adjustment
		• Linearization curve incorrect	• Adapt linearization curve
		• Installation in a bypass tube or standpipe, hence running time error (small measurement error close to 100 %/large error close to 0 %)	• Check parameter "Application" with respect to vessel form, adapt if necessary (bypass, standpipe, diameter)

Fault description	Error pattern	Cause	Rectification
		2. Measured value jumps towards 0 %	
• Multiple echo (vessel top, product surface) with amplitude higher than the level echo	• Check parameter "Application", especially vessel top, product type, dished end, high dielectric figure, adapt if necessary		
3. Measured value jumps towards 100 %		• Due to the process, the amplitude of the product echo sinks • A false signal suppression was not carried out	• Carry out false signal suppression
		• Amplitude or position of a false echo has changed (e.g. condensation, buildup); false signal suppression no longer matches	• Determine the reason for the changed false echoes, carry out false signal suppression, e. g. with condensation

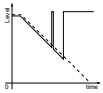
Measurement error during filling

Fault description	Error pattern	Cause	Rectification
4. Measured value remains unchanged during filling		• False echoes in the close range too big or product echo too small • Strong foam or spout generation • Max. adjustment not correct	• Remove false echoes in the close range • Check measurement situation: Antenna must protrude out of the socket, installations • Remove pollution on the antenna • Minimize interfering installations in the close range by changing the polarization direction • Create a new false signal suppression • Adapt max. adjustment
5. Measured value remains in the bottom section during filling		• The tank floor echo is larger than the product echo, e.g. with products with ε_r < 2.5 oil-based, solvents	• Application parameter "Medium", check Vessel height and Floor form, adapt if necessary

Fault description	Error pattern	Cause	Rectification
6. Measured value remains momentarily unchanged during filling and then jumps to the correct level		• Turbulence on the product surface, quick filling	• Check application parameters, change if necessary, e.g. in dosing vessel, reactor
7. Measured value jumps towards 0 % during filling		• Amplitude of a multiple echo (vessel top - product surface) is larger than the level echo	• Check parameter "Application", especially vessel top, product type, dished end, high dielectric figure, adapt if necessary
		• The level echo cannot be distinguished from the false echo at a false echo position (jumps to multiple echo)	• Remove/reduce false echo: minimize interfering installations by changing the polarization direction • Chose a more suitable installation position
8. Measured value jumps towards 100 % during filling		• Due to strong turbulence and foam generation during filling, the amplitude of the product echo sinks. Measured value jumps to the false echo	• Carry out false signal suppression
9. Measured value jumps sporadically to 100 % during filling		• Varying condensation or contamination on the antenna	• Carry out a false signal suppression or increase false signal suppression with condensation/contamination in the close range by editing
10. Measured value jumps to ≥ 100 % or 0 m distance		• Level echo is no longer detected in the close range due to foam generation or false echoes in the close range. The sensor goes into overfill protection mode. The max. level (0 m distance) as well as the status message "Overfill protection" are outputted.	• Check measuring site: Antenna must protrude out of the socket • Remove pollution on the antenna • Use a sensor with a more suitable antenna

Measurement error during emptying

Fault description	Error pattern	Cause	Rectification

Fault description	Error pattern	Cause	Rectification
11. Measured value remains unchanged in the close range during emptying		• False echo larger than the level echo • Level echo too small	• Remove false echoes in the close range. Check: Antenna must protrude out of the socket • Remove pollution on the antenna • Minimize interfering installations in the close range by changing the polarization direction • After removing the false echoes, the false signal suppression must be deleted. Carry out a new false signal suppression
12. Measured value jumps towards 0 % during emptying		• The tank floor echo is larger than the product echo, e.g. with products with ε_r < 2.5 oil-based, solvents	• Application parameter "Medium type", check Vessel height and Floor form, adapt if necessary
13. Measured value jumps sporadically towards 100 % during emptying		• Varying condensation or contamination on the antenna	• Carry out false signal suppression or increase false signal suppression in the close range by editing • With bulk solids use radar sensor with purging air connection

Reaction after fault rectification

Depending on the reason for the fault and the measures taken, the steps described in chapter "*Setup*" must be carried out again or must be checked for plausibility and completeness.

24 hour service hotline

Should these measures not be successful, please call in urgent cases the VEGA service hotline under the phone no. **+49 1805 858550**.

The hotline is also available outside the normal working hours on seven days a week around the clock.

Since we offer this service worldwide, the support is in the English language. The service itself is free of charge, the only costs involved are the normal call charges.

9.5 Exchanging the electronics module

If the electronics module is defective, it can be replaced by the user.

In Ex applications only one instrument and one electronics module with respective Ex approval may be used.

If there is no electronics module available on site, the electronics module can be ordered through the agency serving you. The electronics modules are adapted to the respective sensor and differ in signal output or voltage supply.

The new electronics module must be loaded with the default settings of the sensor. These are the options:

- In the factory
- Or on site by the user

In both cases, the serial number of the sensor is needed. The serial numbers are stated on the type label of the instrument, on the inside of the housing as well as on the delivery note.

When loading on site, first of all the order data must be downloaded from the Internet (see operating instructions manual "*Electronics module*").

9.6 Software update

The following components are required to update the sensor software:

- Sensor
- Voltage supply
- Interface adapter VEGACONNECT 4
- PC with PACTware
- Current sensor software as file

Caution:
Note that due to a software update you can lose approvals.

You can find the actual sensor software as well as detailed information of the procedure on our home page under "www.vega.com/downloads" on "*Software*".

9.7 How to proceed in case of repair

If a repair is necessary, please proceed as follows:

You can download a return form (23 KB) from our homepage at www.vega.com under: "*Downloads - Forms and certificates - Repair form*".

By doing this you help us carry out the repair quickly and without having to call back for needed information.

- Print and fill out one form per instrument
- Clean the instrument and pack it damage-proof
- Attach the completed form and, if need be, also a safety data sheet outside on the packaging
- Please ask the agency serving you for the address of your return shipment. You can find the competent agency on our website www.vega.com.

10 Dismounting

10.1 Dismounting steps

Warning:
Before dismounting, be aware of dangerous process conditions such as e.g. pressure in the vessel, high temperatures, corrosive or toxic products etc.

Take note of chapters "*Mounting*" and "*Connecting to power supply*" and carry out the listed steps in reverse order.

10.2 Disposal

The instrument consists of materials which can be recycled by specialised recycling companies. We use recyclable materials and have designed the electronics to be easily separable.

Correct disposal avoids negative effects on humans and the environment and ensures recycling of useful raw materials.

Materials: see chapter "*Technical data*"

If you have no way to dispose of the old instrument properly, please contact us concerning return and disposal.

WEEE directive 2002/96/EG
This instrument is not subject to the WEEE directive 2002/96/EG and the respective national laws. Pass the instrument directly on to a specialised recycling company and do not use the municipal collecting points. These may be used only for privately used products according to the WEEE directive.

11 Supplement

11.1 Technical data

General data

316L corresponds to 1.4404 or 1.4435

Materials, wetted parts	
– Process fitting - thread, flange	PVDF, 316L, 316L PTFE plated
– Process seal - Thread PVDF	FKM (Viton)
– Process seal - Thread 316L	Klingersil C-4400 (attached)
– Antenna for sockets 50 mm (1.969 in)	PVDF, PTFE
– Antenna for sockets 100 mm (3.937 in) and 250 mm (9.843 in)	PTFE
Materials, non-wetted parts	
– Plastic housing	plastic PBT (Polyester)
– Aluminium die-casting housing	Aluminium die-casting AlSi10Mg, powder-coated - basis: Polyester
– Stainless steel housing	316L
– Seal between housing and housing cover	NBR (stainless steel housing, precision casting), silicone (aluminium/plastic housing; stainless steel housng, electropolished)
– Inspection window in housing cover (optional)	Polycarbonate
– Ground terminal	316L
Ohmic contact	Between ground terminal and metallic process fitting
Process fittings	
– Pipe thread, cylindrical (ISO 228 T1)	G1½ A according to DIN 3852-A with 316L; G1½ A similar to DIN 3852-A-B with PVDF
– American pipe thread, tapered	1½ NPT
– Flanges	DIN from DN 25, ANSI from 1"
Torque of the flange screws (min.)	60 Nm (44.25 lbf ft)
Weight	2 … 15.4 kg (4.409 … 33.95 lbs)
Torque for NPT cable glands and Conduit tubes	
– Plastic housing	max. 10 Nm (7.376 lbf ft)
– Aluminium/Stainless steel housing	max. 50 Nm (36.88 lbf ft)

Input variable

Measured variable	The measured quantity is the distance between process fitting of the sensor and product surface. The reference plane is the seal surface on the hexagon or the lower side of the flange.

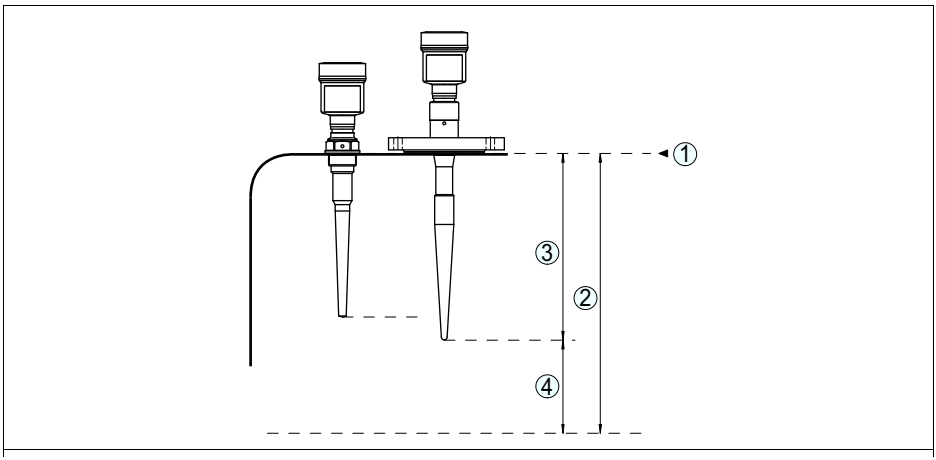


Fig. 35: Data of the input variable

1 Reference plane
2 Measured variable, max. measuring range
3 Antenna length
4 Useful measuring range

Max. measuring range	35 m (114.83 ft)
Recommended measuring range	up to 10 m (32.81 ft)

Output variable

Output signals	4 … 20 mA/HART - active; 4 … 20 mA/HART - passive
Terminal voltage passive	9 … 30 V DC
Shortcircuit protection	Available
Potential separation	Available
Signal resolution	0.3 µA
Failure signal current output (adjustable)	mA-value unchanged 20.5 mA, 22 mA, < 3.6 mA
Max. output current	22 mA
Starting current	≤ 3.6 mA
Load (4 … 20 mA/HART - active)	< 500 Ω
Damping (63 % of the input variable)	0 … 999 s, adjustable
HART output values	
– PV (Primary Value)	Distance to the level
– SV (Secondary Value)	Level as percentage value
– TV (Third Value)	Linearised percentage value
– QV (Fourth Value)	Scaled measured value
Resolution, digital	< 1 mm (0.039 in)

Accuracy (according to DIN EN 60770-1)

Process reference conditions according to DIN EN 61298-1

– Temperature	+18 … +30 °C (+64 … +86 °F)
– Relative humidity	45 … 75 %
– Air pressure	860 … 1060 mbar/86 … 106 kPa (12.5 … 15.4 psig)

Installation reference conditions

– Min. distance to installations	> 200 mm (7.874 in)
– Reflector	Corner reflector
– False reflections	Largest false echo 20 dB smaller than the useful echo

Deviation with liquids — See following diagrams

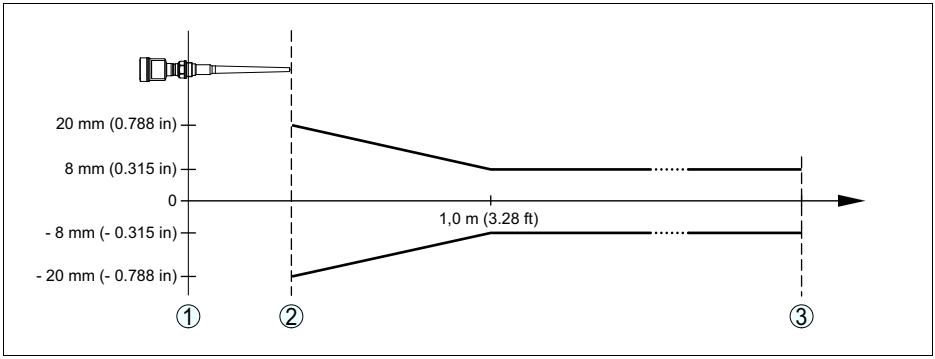


Fig. 36: Deviation under reference conditions

1 Reference plane
2 Antenna edge
3 Recommended measuring range

Reproducibility — ≤ ±1 mm

Variables influencing measurement accuracy

Specifications apply to the HART signal and the current output

Temperature drift - Digital output	±3 mm/10 K relating to the max. measuring range or max. 10 mm
Additional deviation through strong, high frequency electromagnetic fields acc. to EN 61326	<±50 mm

Specifications apply also to the current output

Temperature drift - Current output	±0.03 %/10 K relating to the 16 mA span max. ±0.3 %
Deviation on the current output by analogue/ digital conversion	<±15 µA

Deviation on the current output by strong, high frequency electromagnetic fields within EN 61326	<±150 µA

Characteristics and performance data

Frequency	C-band (6 GHz technology)
Measuring cycle time approx.	350 ms
Step response time[1]	≤ 3 s
Tracking speed of the measuring window max.	1 m/min
Beam angle[2]	24°
Emitted HF power (depending on the parameter adjustment)[3]	
– Average spectral transmission power density	-31 dBm/MHz EIRP
– Max. spectral transmission power density	+24 dBm/50 MHz EIRP
– Specific absorption rate (SAR)	0.47 mW/kg

Ambient conditions

Ambient, storage and transport temperature	-40 … +80 °C (-40 … +176 °F)

Process conditions

For the process conditions, please also note the specifications on the type label. The lower value always applies.

Process temperature (measured on the process fitting)	
– Process fitting, thread PVDF	-40 … +130 °C (-40 … +266 °F)
– Other process fittings	-40 … +150 °C (-40 … +302 °F)
Vessel pressure	
– Screwed part PVDF	-1 … 2 bar (-100 … 200 kPa/-14.5 … 29.0 psig)
– Screwed part and flange 316L	-1 … 16 bar (-100 … 1600 kPa/-14.5 … 232 psig)
Vessel pressure relating to the flange nominal stage	see supplementary instructions manual "*Flanges according to DIN-EN-ASME-JIS*"
Vibration resistance	4 g at 5 … 200 Hz according to EN60068-2-6 (vibration with resonance)
Shock resistance	100 g, 6 ms according to EN60068-2-27 (mechanical shock)

1) Time span after a sudden measuring distance change by max. 0.5 m in liquid applications, max 2 m with bulk solids applications, until the output signal has taken for the first time 90 % of the final value (IEC 61298-2).
2) Outside the specified beam angle, the energy of the radar signal has a level which is reduced by 50 % (-3 dB)
3) EIRP: Equivalent Isotropic Radiated Power

Electromechanical data - version IP 66/IP 67

Cable entry	
– Double chamber housing	• 1 x cable entry M20 x 1.5 (cable: ø 5 … 9 mm), 1 x blind stopper M20 x 1.5; 1 x blind stopper M16 x 1.5 or optional[4]1 x plug M12 x 1 for external indicating and adjustment unit or: • 1 x closing cap ½ NPT, 1 x blind stopper ½ NPT, 1 x blind stopper M16 x 1.5 or optionally[5]1 x plug M12 x 1 for external indicating and adjustment unit or: • 1 x plug (depending on the version), 1 x blind stopper M20 x 1.5; 1 x blind stopper M16 x 1.5 or optionally[6]1 x plug M12 x 1 for external indicating and adjustment unit
Spring-loaded terminals for wire cross-section	
– Massive wire, cord	0.2 … 2.5 mm² (AWG 24 … 14)
– Stranded wire with end sleeve	0.2 … 1.5 mm² (AWG 24 … 16)
– Two stranded wires with double end sleeve, each	0.2 … 1.5 mm² (AWG 24 … 16)

Indicating and adjustment module

Voltage supply and data transmission	through the sensor
Indication	LC display in dot matrix
Measured value indication	
– Number of digits	5
– Size of digits	W x H = 7 x 13 mm (sensors with software ≥ 4.0.0, hardware ≥ 2.0.0) W x H = 5 x 8 mm (sensors with software ≤ 3.99, hardware < 2.0.0)
Adjustment elements	4 keys
Protection rating	
– unassembled	IP 20
– mounted into the sensor without cover	IP 40
Materials	
– Housing	ABS
– Inspection window	Polyester foil

4) Only with Ex d version
5) Only with Ex d version
6) Only with Ex d version

Integrated clock	
Date format	Day.Month.Year
Time format	12 h/24 h
Time zone Ex factory	CET

Measurement electronics temerature	
Resolution	1 °C (1.8 °F)
Accuracy	±1 °C (1.8 °F)

Voltage supply	
Operating voltage	
– Version for low voltage	9.6 … 48 V DC, 20 … 42 V AC, 50/60 Hz
– Version for mains voltage	90 … 253 V AC, 50/60 Hz
Interpolation protection	Available
Max. power consumption	4 VA; 2.1 W

Electrical protective measures	
Protection rating	IP 66/IP 67
Overvoltage category	III
Protection class	I

Approvals

Instruments with approvals can have different technical data depending on the version.

That's why the associated approval documents have to be noted with these instruments. They are part of the delivery or can be downloaded under www.vega.com via "*VEGA Tools*" and "*serial number search*" as well as via "*Downloads*" and "*Approvals*".

11.2 Dimensions

The following dimensional drawings represent only an extract of the possible versions. Detailed dimensional drawings can be downloaded on www.vega.com under "*Downloads*" and "*Drawings*".

Housing

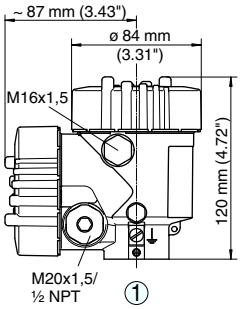


Fig. 37: Dimensions housing - with integrated indicating and adjustment module the housing is 9 mm/0.35 in higher

VEGAPULS 65

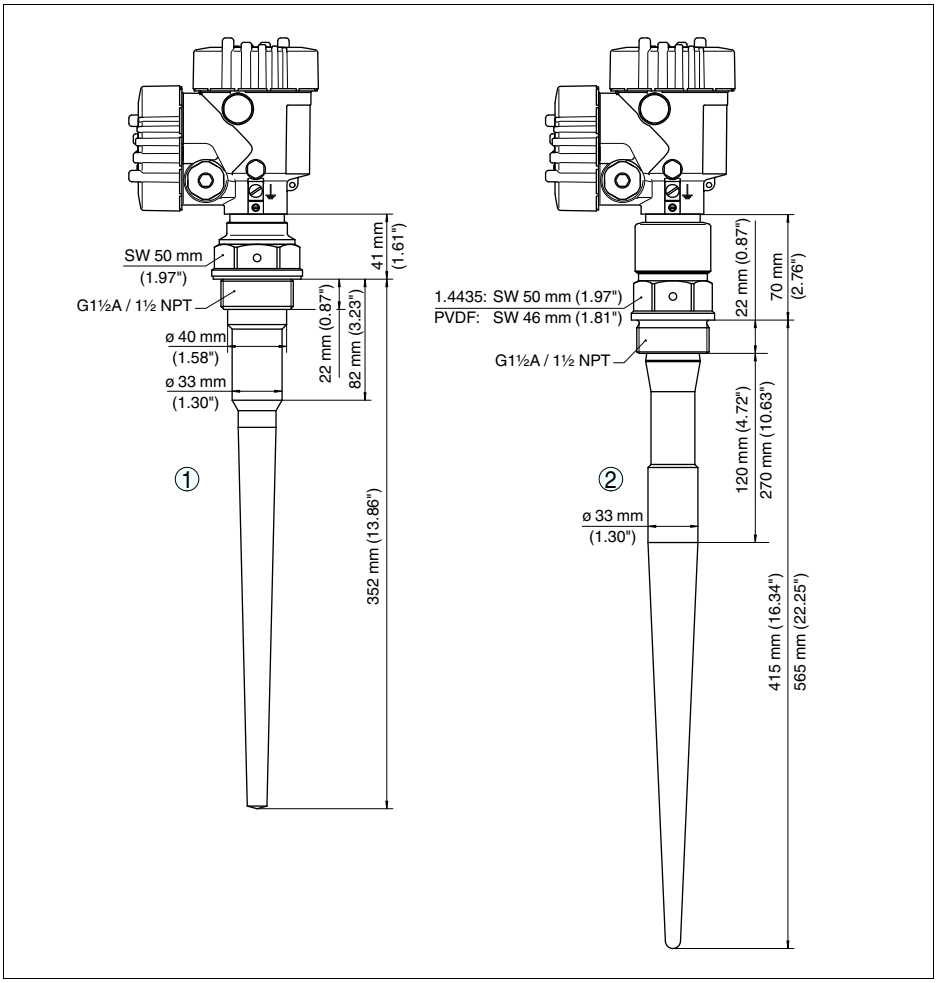


Fig. 38: VEGAPULS 65, threaded version

1 Thread and hexagon of PVDF for sockets with 50 mm height (inactive length 82 mm, 55/64")
2 Thread and hexagon of PVDF or 316L for sockets with 100 mm height (inactive length 120 mm, 4 23/32") or 250 mm height (inactive length 270 mm, 10 5/8")

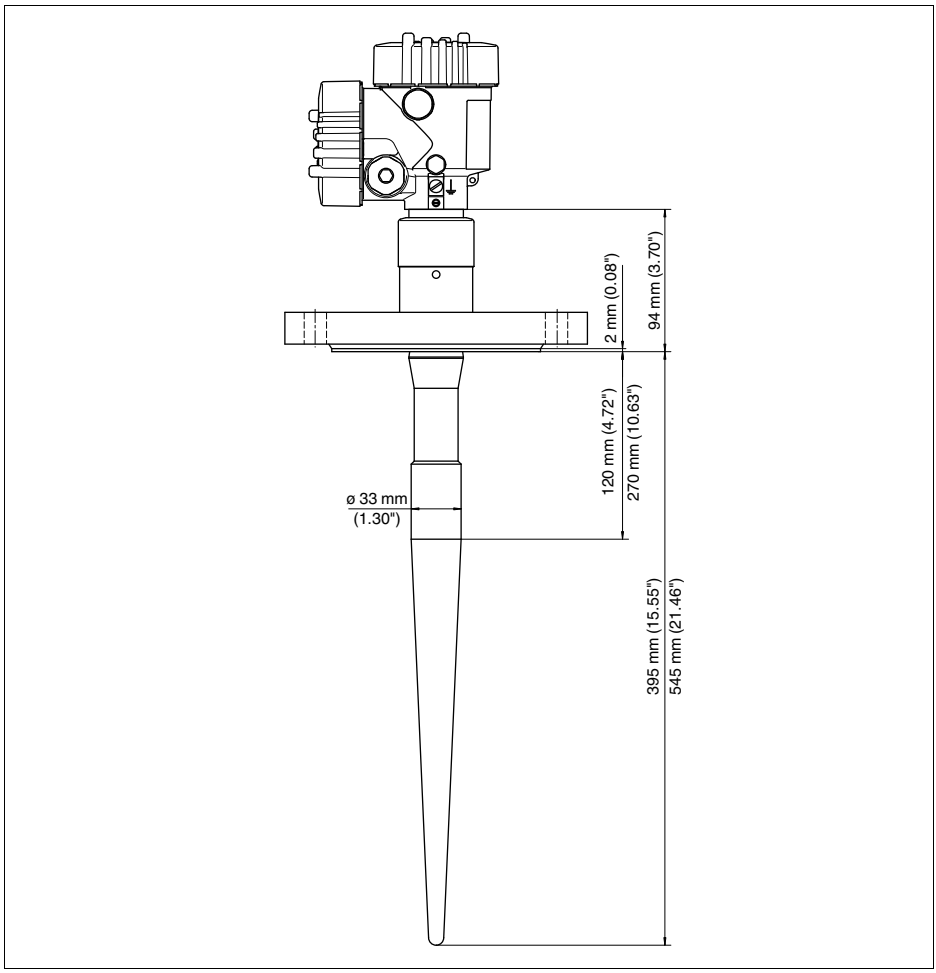


Fig. 39: VEGAPULS 65, flange version for sockets with 100 mm height (inactive length 120 mm, 4 23/32") or 250 mm height (inactive length 270 mm, 10 5/8")

11.3 Industrial property rights

VEGA product lines are global protected by industrial property rights. Further information see http://www.vega.com.
Only in U.S.A.: Further information see patent label at the sensor housing.

VEGA Produktfamilien sind weltweit geschützt durch gewerbliche Schutzrechte.
Nähere Informationen unter http://www.vega.com.

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进一步信息请参见网站<http://www.vega.com>。

11.4 Trademark

All the brands as well as trade and company names used are property of their lawful proprietor/originator.

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